

performers install a sensor kit containing an Arduino UNO board [8] running a sketch (program) that reads analog sensor data and sends it to a serial object in the virtual Swallow World via a Max/MSP patch. Attached to the Arduino board are three different sensors:

- LDR (light dependent resistor) to measure gradations of light in each location.
- Temperature sensor (DS1820 Dallas 1-Wire Digital Thermometer requiring OneWire.h and DallasTemperature.h libraries on Arduino). It measures fluctuations in temperature in each location and sends the data to each performer in the virtual Sea Swallow world.
- A three-axis accelerometer (MMA7361LC) fitted to a wristband streams hand and wrist positions to the virtual hands, allowing networked performers to visually cue their movement in the virtual world.

Connecting the virtual environment of the Swallow World to the networked locations in Sydney, New York and Braunschweig is a patch that displays the motion data as 3D hand models in OpenGL graphics. The patch receives the motion data of all three performers and controls the virtual hands, allowing them to move and change colour for navigation (on/off, forward/backward, or stop). The patch also receives data for each remote POV in the Swallow World, calculated by the Navigation Control patch in the performance venue to synchronise all three virtual Swallow Worlds. The patch also receives the processed video stream from the database and streams it into the performance space in Braunschweig, Germany. The telematic audio interface eJamming provides the networked audio system, and real-time video streaming of dispersed performers is via mpeg-4 compressed video.

Navigation Control

Controlling performers' navigation in the virtual environment is a patch that receives the data from the three dispersed motion sensors. As soon as one performer is in navigation mode, the patch uses this motion data to control all POV parameters in the Swallow World. This is achieved through the modification of the `z.glNav` abstraction code from Zachary Seldess [11]. When more than one performer switches on navigation mode, the patch automatically calculates the average distance of each performer and their proximity to the virtual audio-visual spheres.

Preparation and Performances

Preparation for the performances required a number of rehearsal sessions in which performers familiarised themselves with the technology and remote navigation of the virtual environment. While the system had been trialed during construction, expanding it over multiple nodes necessitated further technological refinement. This included adapting the parameters of the accelerometers to performers' physical experiences of using them, e.g. speed, and spatial orientation, as well as modifying the algorithms used for controlling the playback of database audio-visual files based on performers' proximity to them. Likewise each performer went through a process of learning how to use the wristband and sensors to navigate the virtual Sea Swallow environment—specifically,

navigating in a 'swarm,' in which dispersed performers moved their virtual hands remotely to traverse the virtual environment together. This produced some interesting results, such as the experience of hand and wrist movements being locked together, despite the geographical separation of performers. Notable, too, were the extremes of lighting states produced by evening and daytime performances, and the temperature fluctuations of the Northern and Southern performer locations.

The performances featured networked musicians—guitarist Marc Sloan (New York) and trumpeter Roger Mills (Sydney)—improvising with percussion and electronics artist Martin Slawig and vocalist and electronics artist Elke Utermöhlen, who were performing to a live audience in Braunschweig, Germany. Semi-scripted instructions provided a basic structure for the performances, including navigation and interaction with the virtual environment in which the performers responded in freely improvised music [12]. Audiences were also given the opportunity to try on the wristband accelerometers and interact with the virtual environment after each performance. This provided insights into the ways in which a cross-section of uninitiated participants conceptualised the performance and adapted to moving within the virtual environment. For example, people with gaming experience controlled the interface more readily than those without gaming experience.

Discussion and Future Work

Flight of the Sea Swallow is an example of a cross-reality virtual environment as a venue for telematic audiovisual performance. The project illustrates the ways in which the visualisation of real-world data from dispersed networked locations can augment performers' interaction, leading to increased tele-presence and creative engagement. Future work is required to examine the potential of using additional informational data flows (e.g. humidity, air quality), as well as the potential for sonifying this data for musical interpretation. As a first step, *Flight of the Sea Swallow* has provided a practice-based approach to understanding the potential use of cross-reality environments in NMP and the ways in which this can be developed further.

References and Notes

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