Robot-assisted septal myectomy for hypertrophic cardiomyopathy with left ventricular outflow tract obstruction

Zain Khalpey, MD, PhD, MRCS (Eng)a, Lev Korovin, BSa, W. Randolph Chitwood Jr, MD, FACS, FRCSb, and Robert Poston, MDa

aDivision of Cardiothoracic Surgery, Department of Surgery, University of Arizona College of Medicine, Tucson, Ariz

bEast Carolina Heart Institute, East Carolina University, Pitt County Memorial Hospital, Greenville, NC

Hypertrophic cardiomyopathy is a relatively common disease caused by genetic mutations that disrupt the sarcomere components. Although frequent in younger patients, it can present from infancy to old age. Its natural history can include sudden cardiac death, arrhythmias, and heart failure.1 Severe heart failure symptoms can result from left ventricular outflow tract (LVOT) obstruction, with or without systolic anterior motion of the mitral valve apparatus. For patients with LVOT obstruction, the outflow tract pressure gradient can be reduced using interventional techniques that have included surgical septal myectomy and alcohol septal ablation. According to a recent meta-analysis, septal myectomy has been superior in terms of reducing the gradient and preventing persistent conduction abnormalities.2

The initial reports of myectomy for symptomatic patients with LVOT obstruction described septal exposure by way of a left atriotomy and takedown of the anterior mitral leaflet. Given the challenge of septal visualization, this traditional approach was abandoned for the current standard, the Morrow procedure, which involves access to the ventricular septum by way of an aortotomy across the aortic valve. Two major limitations of both these procedures have been the required sternotomy and associated prolonged postoperative recovery.

Surgical robotics has been used to routinely access the mitral valve by way of a left atriotomy. Therefore, a similar approach could be used to reintroduce the transatrial, transmitral approach to the hypertrophic septum. We have described a septal myectomy performed with a less-invasive, robot-assisted approach in a patient with recurrent symptomatic LVOT obstruction who had previously undergone an alcohol ablation procedure.
The patient’s preoperative echocardiogram demonstrated systolic anterior motion of the mitral valve chordate with an LVOT gradient of 20 to 30 mm Hg that increased to 61 mm Hg with the Valsalva maneuver. The maximum septal thickness was measured at 16.5 mm using computed tomography. Moreover, the patient had class III heart failure symptoms despite maximal medical therapy.

After deflating the patient’s right lung, we inserted 3 ports at the third, fifth, and seventh intercostal spaces. We docked the robot to those ports using a topographic approach similar to that described by Chitwood. After systemic heparinization, we instituted cardiopulmonary bypass using femoral artery and vein cannulation. With both lungs deflated, we used robotic instruments to open and tack the pericardium to the chest wall. We dissected Sondergaard’s groove to separate the left and right atria and then induced cardioplegia using ascending aorta cannulation in an antegrade manner.

Next, we incised the left atrium and inserted the left atrial retractor. The mitral valve was normal on inspection. We opened the anterior leaflet (Figure 1, A) and identified the septum and aortic valve (Figure 1, B). The previously ablated portion of the septum was clearly visible by the extensive scarring. We removed 3 strips of the copiously scarred ablated septum, which lacked normal myocardial tissue (Figure 1, C). We reapproximated the anterior leaflet with Gore-Tex 5-0 suture (W. L. Gore & Associates, Flagstaff, Ariz) and then tested the valve for leakage.

Finally, we closed the left atrium, removed the cross-clamp, and performed de-airing maneuvers. Initially, we observed signs of a spontaneous rhythm; however, subsequently, complete heart block developed. Therefore, we paced the patient ventricularely, using a pacing wire to the inferior aspect of the right ventricle. The LVOT gradient was reduced; we no longer observed systolic anterior motion. The patient was successfully weaned off cardiopulmonary bypass. Postoperatively, the patient required placement of a permanent pacemaker for persistent complete heart block; however, she had returned to a normal sinus rhythm 1 month postoperatively. The immediate postoperative echocardiogram showed an LVOT gradient of 15 mm Hg. At her 4-month follow-up visit, we noted no significant intracavitary gradient. The postoperative septal thickness was 0.98 cm, and the distance between the mitral–septal contact point and the aortic annulus was 1.0 cm.

The Morrow procedure uses a midline sternotomy, with the left ventricle and septum accessed by the aortic valve through a vertical aortotomy. The potential limitations of the procedure include small, but persistent, risks of an aortotomy (eg, postoperative bleeding, aortic dissection), difficulties with visualizing the surgical anatomy, and the risk of aortic valve damage (approximately 5% rate of moderate aortic regurgitation postoperatively).

A robotic approach using the left atrium and across the mitral valve is an alternative and more direct route to the ventricular septum that can circumvent the limitations of the standard transaortic approach. The required robotic manipulation of the mitral valve for left
ventricular septum access seems less risky than the transaortic route across the often friable aortic valve for provoking valvular damage.

Although additional studies are needed to evaluate the frequency of associated complications, our robot-assisted technique could be an acceptable alternative to the Morrow procedure.

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References

FIGURE 1.
A, Opening the mitral valve anterior leaflet. Curved robotic scissors were used to incise the anterior leaflet, proceeding counterclockwise in a radial fashion from the right fibrous trigone to the left fibrous trigone. B, Exposure of the interventricular septum and aortic valve through the mobilized mitral valve anterior leaflet. C, Resection of the previously ablated fibrotic interventricular septum. The rectangular resected tissue was extended clockwise from near the left fibrous trigone to the nadir of the right coronary cusp.