

## Problem 1

### Levenberg-Marquardt scheme

1. In the first part of this question, I would like you to generate an exponentially decaying data,

$$5 e^{-0.2t}, \quad (1)$$

where  $t \in [0, 10]$ . Add random Gaussian noise so that you obtain a noisy decaying exponential. Plot this decay.

2. We would like to fit this fabricated data to an exponential decay,

$$x_1 e^{-x_2 t}, \quad (2)$$

where the unknown parameters are  $\vec{\mathbf{x}} = (x_1, x_2)$ . Now I would like you to write a computer program employing the Levenberg-Marquardt scheme, which specifies that the parameters are updated according to

$$\mathbf{x}_{k+1} = \mathbf{x}_k - (H(x_k) + \beta \text{diag}(H(x_k)))^{-1} \vec{\nabla} \chi^2. \quad (3)$$

Find  $\chi^2$ ,  $\vec{\nabla} \chi^2$ , and the Hessian  $H(\vec{x})$ , and where  $\text{diag}(H)$  is a fixed diagonal matrix with the same elements as  $H$ .

Note that in the Levenberg-Marquardt algorithm, the value of  $\beta$  is also changed iteratively. Implement the following scheme.

- (a) Pick an initial guess for  $\mathbf{x}$ , and  $\beta = 0.01$  (say).
  - (b) Find  $\chi^2(\vec{\mathbf{x}})$ .
  - (c) Compute  $\delta \vec{\mathbf{x}} = -(H + \beta \text{diag}(H))^{-1} \vec{\nabla} \chi^2$ .
  - (d) Find  $\chi^2(\vec{\mathbf{x}} + \delta \vec{\mathbf{x}})$ .
  - (e) If  $\chi^2(\vec{\mathbf{x}} + \delta \vec{\mathbf{x}}) \geq \chi^2(\vec{\mathbf{x}})$ , increase  $\beta$  by a factor of 10 and go back to step (c).
  - (f) If  $\chi^2(\vec{\mathbf{x}} + \delta \vec{\mathbf{x}}) < \chi^2(\vec{\mathbf{x}})$ , decrease  $\beta$  by a factor of 10 and update the trial  $\vec{\mathbf{x}} \rightarrow \vec{\mathbf{x}} + \delta \vec{\mathbf{x}}$  and go to step (c).
  - (g) Terminate if  $\chi^2$  does not change by a value greater than some threshold, e.g.  $10^{-10}$  etc.
3. What is your best estimate of the parameter  $\vec{\mathbf{x}}$ ?

## Problem 2

Question 7.5 from Hughes, "Measurements and their Uncertainties".

### Problem 3

Question 7.7 from Hughes, "Measurements and their Uncertainties".

### Problem 4

Question 7.8 from Hughes, "Measurements and their Uncertainties".

### Problem 5

A student varies the orientation of a polarizer in steps of  $10^\circ$ , starting from  $0^\circ$  and going up to  $270^\circ$ . Polarized laser light passes through the polarizer and falls on a detector which measures the following intensities (in the same order and in arbitrary units).

Intensity = {0.0558, -0.0274, -0.1127, -0.2253, -0.2098, -0.2725, -0.3086, -0.2611, -0.2681,  
-0.2607, -0.1492, -0.0891, -0.0157, 0.0506, 0.1276, 0.1229, 0.2285, 0.2074, 0.1596,  
0.1071, 0.0166, -0.0053, -0.1177, -0.2067, -0.2031, -0.2898, -0.3173, -0.3006}.

I propose that a suitable fit for the data-set is

$$\text{Intensity} = A + B \cos^2(C\theta + D),$$

where  $\theta$  is the polarizer angle in radians. Use simulated annealing to find the best estimate of  $\{A, B, C, D\}$ . Decrease the temperature, by say, 1% at each step of the iterative annealing process.